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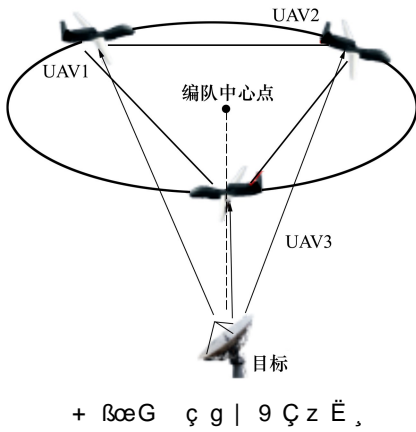
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8, 4L†• : Ō" F : L->50;~ \$ #K!+±9
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t Ç Gg | 9 Ç z N, 1 »] ð/§K!;! >ÿ} 4
 2(Z", 4+±L Ē } 4 g x_i = x_i "y_i "z_i Ö" ç g >ĩ
 "x0 +±} 4 g x_i = x_i "y_i "z_i Ö"i = ß"0" %1 ç g
] , 4 x K!+±C.è g
 $\rho_i = \dot{\Delta}x_i - x_i \dot{\Delta}$

$$\rho_i = \sqrt{\rho_{x_i}^2 + \rho_{y_i}^2 + \rho_{z_i}^2}$$

$$\begin{cases} r^0 = \rho_{x_i}^0 + y_i^0 + z_i^0 \\ r_i^0 = \rho_{y_i}^0 + y_i^0 + z_i^0 \end{cases}$$

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$$\rho_i^0 - r_i^0 - r^0 = - \rho_{x_i}^0 x_i + y_i y_i + z_i z_i$$

$$\begin{cases} \rho_{\beta}^0 - r_{\beta}^0 - r^0 = - \rho_{x_{\beta}}^0 x_{\beta} + y_{\beta} y_{\beta} + z_{\beta} z_{\beta} \\ \rho_0^0 - r_0^0 - r^0 = - \rho_{x_0}^0 x_0 + y_0 y_0 + z_0 z_0 \\ \rho^0 - r^0 - r^0 = - \rho_{x_0}^0 x_0 + y_0 y_0 + z_0 z_0 \end{cases}$$

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g- Kb• < 6

$$A_{\beta} x_i = B_{\beta} \quad \%&<$$

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$$B_{\beta} = \begin{bmatrix} \rho_{\beta}^0 - r_{\beta}^0 - r^0 \\ \rho_0^0 - r_0^0 - r^0 \\ \rho^0 - r^0 - r^0 \end{bmatrix} \quad \text{œ} A_{\beta} = \begin{bmatrix} - \rho_{\beta} & - \rho_{\beta} & - \rho_{\beta} \\ - \rho_0 & - \rho_0 & - \rho_0 \\ - \rho & - \rho & - \rho \end{bmatrix}$$

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$$x_1 = A_{\beta}^{-1} B_{\beta} \quad \%&<$$

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B' "xC A œ %&_{\rho_i} o ± ' Ç z æ/8 g

$$\rho_i = \dot{\Delta}x_i - x_i \dot{\Delta} + \varepsilon_{\rho_i} \quad \%&<$$

œœ ε_{\rho_i} ~ N %b "σ_{\rho}^0 o %3 0v < ± Dæ x₁ 1 E = y

$$Uf•ç, - \varepsilon^{**} P NM! \quad \ddot{\Delta}]$$

$$\rho_i = \dot{\Delta}x_i - x_i \dot{\Delta} - \frac{\rho_{y_i} - y_i}{\dot{\Delta}x_i - x_i \dot{\Delta}} \rho_{y_i} - \frac{\rho_{z_i} - z_i}{\dot{\Delta}x_i - x_i \dot{\Delta}} \rho_{z_i}$$

$$\rho_i = \frac{\rho_{y_i} - y_i}{\dot{\Delta}x_i - x_i \dot{\Delta}} \rho_{y_i} - \frac{\rho_{z_i} - z_i}{\dot{\Delta}x_i - x_i \dot{\Delta}} \rho_{z_i} + \varepsilon_{\rho_i}$$

7 ' Ä] J ' Ç z æ/8 "Æ = - Kb+±• < - 8

$$Ay = B \quad \%&<$$

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$$A = \begin{bmatrix} \frac{x_{\beta} - x_1}{\rho_{\beta}^M} & \frac{y_{\beta} - y_1}{\rho_{\beta}^M} & \frac{z_{\beta} - z_1}{\rho_{\beta}^M} \\ \frac{x_0 - x_1}{\rho_0^M} & \frac{y_0 - y_1}{\rho_0^M} & \frac{z_0 - z_1}{\rho_0^M} \\ \frac{x - x_1}{\rho^M} & \frac{y - y_1}{\rho^M} & \frac{z - z_1}{\rho^M} \end{bmatrix} \quad \text{œ} y = \begin{bmatrix} x_i - x_1 \\ y_i - y_1 \\ z_i - z_1 \end{bmatrix}$$

$$B = \begin{bmatrix} \rho_{\beta}^M - \rho_{\beta} + \varepsilon_{\rho_{\beta}} \\ \rho_0^M - \rho_0 + \varepsilon_{\rho_0} \\ \rho^M - \rho + \varepsilon_{\rho} \end{bmatrix} \quad \text{œ} \dot{\Delta}x_i - x_i \dot{\Delta} = \rho_i^M$$

1" i » %&< " !o ' J ' Ç z æ/8 +±?

$$y \hat{A} = A^{-1} B \quad \%&<$$

J ' ? y \hat{A} %&g 8 ' ± EMæ/8 +±• > ó 4 %

ç g >ĩ "x0 0 mA g μ_i "A\$ B à μ_i ~

N %b "σ_i^0 o "B' æ/8 %&< E 59 Ä] - 3ö+±Ç z æ/8

$$\left[\frac{x_i - x_1}{\rho_i^M} - a_i \mu_i \quad \frac{y_i - y_1}{\rho_i^M} - b_i \mu_i \quad \frac{z_i - z_1}{\rho_i^M} - c_i \mu_i \right] \frac{1}{2}$$

$$\begin{bmatrix} x_i - x_1 \\ y_i - y_1 \\ z_i - z_1 \end{bmatrix} = \rho_i^M - d_i \mu_i - \rho_i + \varepsilon_{\rho_i} \quad \%&<$$

$$C_B = Qy^T C_0 = QA H_y^{-B} \mu x \% \varepsilon Z$$

$$\begin{cases} C_B = (c_{B3} \ c_{B0} \ c_B) \\ C_0 = (c_{03} \ c_{00} \ c_0) \end{cases} \% \beta_0$$

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$$\hat{\lambda} = U[k] = \left[\begin{matrix} \textcircled{R} & \frac{6x_0^0 W}{c_{B0}^0 \mu_i + \lambda 0^0} \\ \textcircled{R} & \frac{c_B^0}{c_{B0}^0 \mu_i + \lambda 0^0} \end{matrix} \right] \% 00$$

f > i 50' ([Ö'E6 λ ±± i g

$$\hat{\lambda} = \frac{\beta}{0} \left[\frac{6x_0^0 W}{c_{B0}^0 \mu_i} + \frac{\beta}{0} \right] U \left[\frac{6x_0^0 W}{c_{B0}^0 \mu_i} \right] \% 00$$

3 i • λ ±± i ' Ç z ? ±± ± • Dë < Ä] Ç z ? g

$$y_{Ai} = \left(A H_y^{-0} A + \left(\frac{\beta}{0} \right) \left[\frac{6x_0^0 W}{c_{B0}^0 \mu_i} + \frac{\beta}{0} \right] U \left[\frac{6x_0^0 W}{c_{B0}^0 \mu_i} \right] \right)^{-\beta} A H_y^{-0} B \% x0$$

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$$\delta \rho = \rho \%_{\rho} "y_i "z_i o - \rho \%_{\rho} "y_i "z_i o =$$

$$\varepsilon \frac{\delta \rho}{\delta x_1} + \varepsilon \% 00$$

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$$\delta \rho = H \delta x + \varepsilon \% 00$$

< Z

$$H = \left[\begin{matrix} \frac{x_i - x_1}{\rho_i^M} - a_i \frac{1}{4} \mu x_i \varepsilon \frac{y_i - y_1}{\rho_i^M} - b_i \frac{1}{4} \mu x_i \\ \varepsilon \frac{z_i - z_1}{\rho_i^M} - c_i \frac{1}{4} \mu x_i \end{matrix} \right] \% 00$$

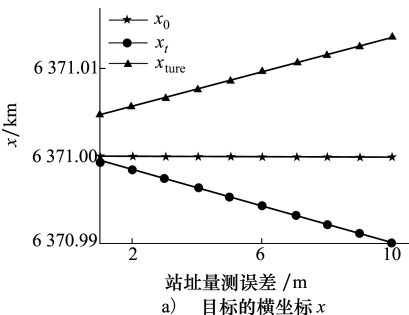
$$\varepsilon = d_i \mu x_i - \varepsilon_{\rho_i} \% 00$$

Dpi] " Ä]

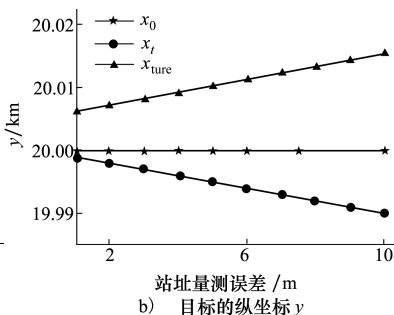
$$\delta \rho = H \delta x \% 00$$

& % 0 o < 0v \$ QDæ ... H^{-β} 6

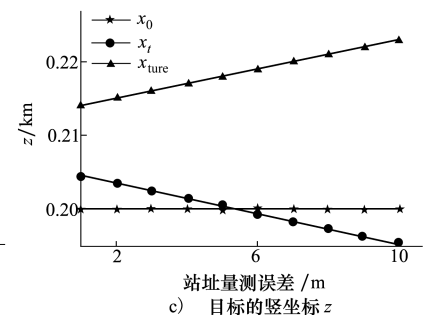
$$\delta x = H^{-\beta} \delta \rho \% x! 0$$



a) 目标的横坐标 x



b) 目标的纵坐标 y



c) 目标的竖坐标 z

A | æ g

6%δxδx o = H^{-β} 6%δρδρ o %M o^{-β} %xβo
ææ g HÖ ê ò C & >ÿ p 2M6 " t @ë
6%δρδρ o ζ : ,% A æ ,%9 t g β" F 6

$$6\% \delta x \delta x o = \% M H o^{-\beta} \% x 0$$
$$x_{H\ddot{O}\ddot{e}} = \sqrt{\text{var}(6\% \delta x \delta x o)} \% x 0$$

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#Ž± , ,L Ž #

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$$\begin{cases} \sigma_i^0 = \sigma_{\beta}^0 \\ \sigma_{\rho}^0 = \sigma_0^0 \end{cases} \varepsilon \% = \beta " 0 " o$$

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, 4 ±± L Ë z 4 > g x_{\text{me}} = \% \textcircled{R} " 0 ! " ! 0o " ā ç g ±± J ø z 4 > = • β m.g " , z g '] % ' » Y ' ý ' ±± Ç z 0Ä" " ü N A O' Z 0 m F ü " x A i » g K ! " ! ! β '] Ö , 4 ±± T 7 ! z 4 > x_1 = x_1 " y_1 " z_1 Ò ÷ , 4 ±± o ? } 4 x_i = x_i " y_i " z_i Ò - + 0 m.g %

$$= \cdot \text{Ó} \text{ ç g ±± J ø z 4 >$$

ç g 4C\$	0 m } 4 ð]
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	% \textcircled{R} " Ž " 0 ! " Ž " β o

+ 0æ , 4 ±± T 7 ! z 4 > ÷ Ç z ?

